

Walker C1 Quick Start Guide

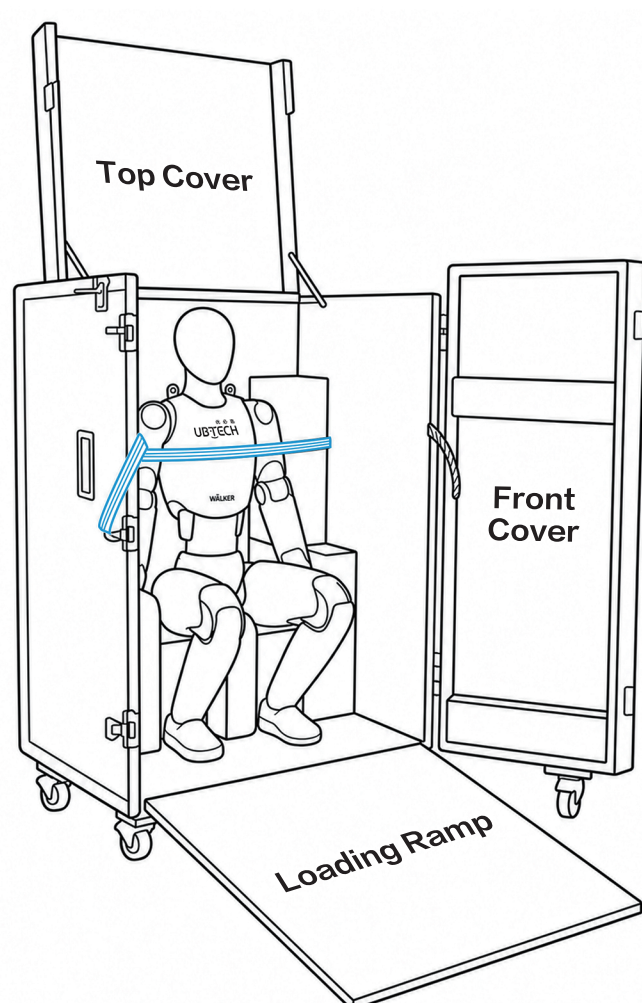


Figure 1

1 Pre-unboxing Preparation

To ensure operational safety, it is recommended to watch the instructional video before operating. Two-person collaboration is advised. Ensure a single-machine operation area of $\geq 4\text{m}^2$ ($2\text{m} \times 2\text{m}$) and a collaboration aisle width of $\geq 1.5\text{m}$.

1. Lock the wheels on both sides and the rear of the flight case, open the top cover of the flight case, and remove the EPE foam above and in front of the robot (Figure 1)
2. Open the front cover of the flight case, unfasten the fixing straps, and lower the loading ramp (Figure 1)

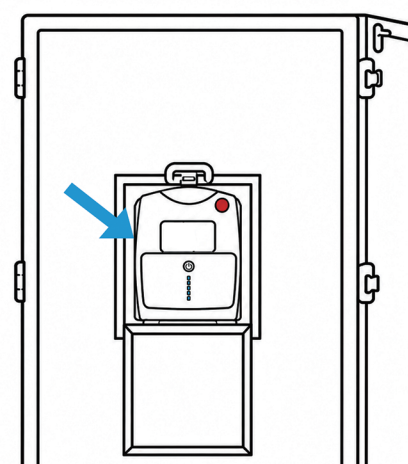


Figure 2

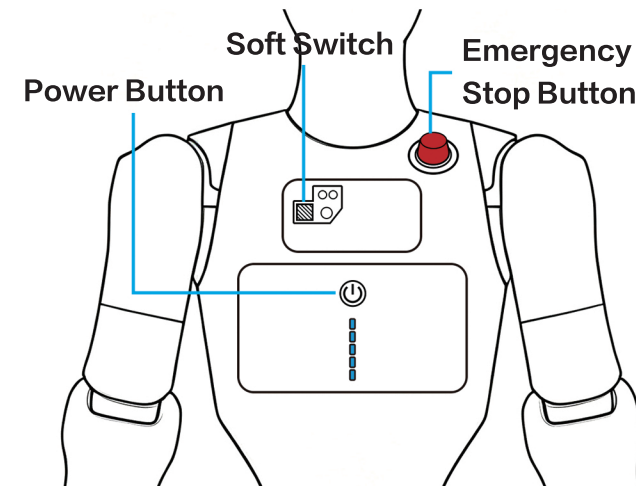


Figure 3

2 Power On

1. Open the small door on the rear cover of the flight case. Press and hold the power button on the robot's back for 5 seconds, then wait until the power indicators remain steadily lit (Figure 2)
2. Remove the cover plate above the power button. Press and hold the square soft switch until the rear fan starts spinning and hot air blows out, then release (Figure 3)
3. The head display lighting up indicates that the robot is starting up; the startup takes approximately 2 minutes

For routine startup procedures and detailed feature descriptions, please scan the QR code to view the complete Product User Manual

3 Step Out

1. Once the robot announces "Entered remote control mode. You may now start using it," unfasten the safety belt on the robot
2. Remove the remote controller from the EPE foam, then press and hold its power button to power it on; once the cross mark disappears from the signal icon in the upper-left corner of the screen, the connection is successful
3. Before remote control operation, verify that there are no obstacles within 1 meter around the loading ramp.(Figure 4)
4. Hold SE and push T4 left, then wait for the robot to stand up on its own, step out of the case, and walk down the loading ramp onto flat ground until it comes to a steady stance — this indicates a successful unboxing (Figure 5)

To use the hoist for power-on and unboxing, please scan the QR code to view the complete product manual

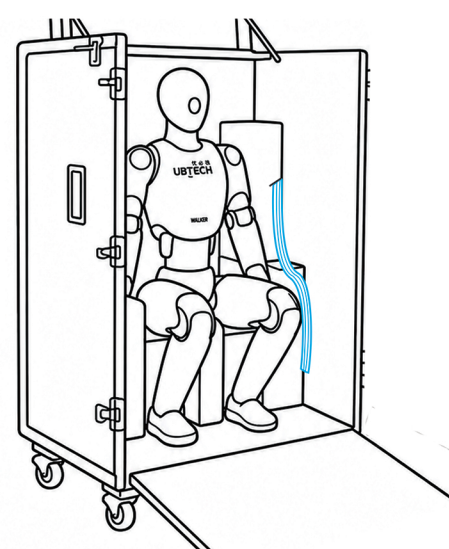


Figure 4

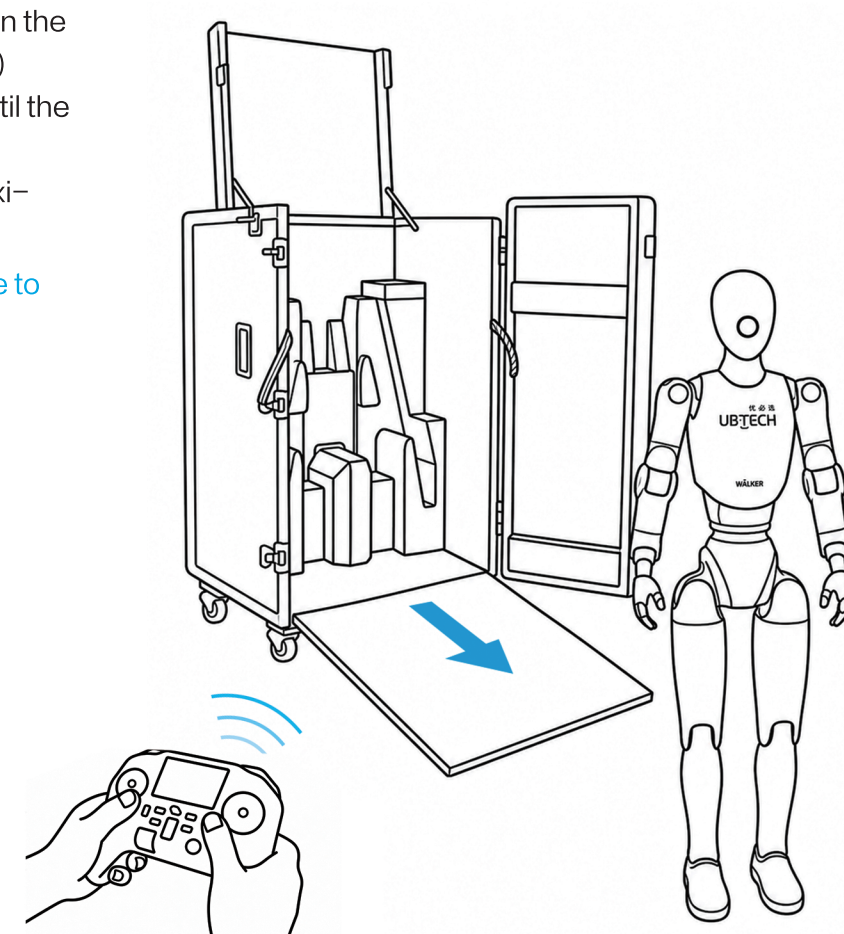


Figure 5

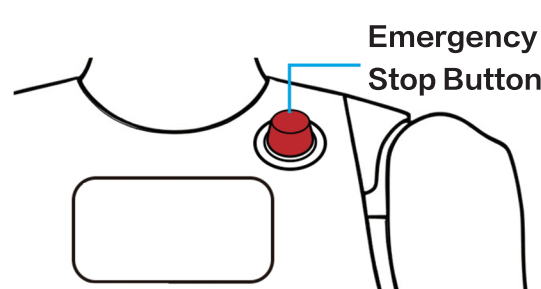


Figure 6

4 Emergency Stop

1. In the event of an emergency, immediately press down the emergency stop button on the back of the robot to lock all motors.(Figure 6)
2. Note: Once the emergency stop button is pressed, the robot can no longer balance on its own; lift the robot with the hoist, then power it off and restart it.

5 Power Off

1. Using the remote controller, first switch the robot to **Force-Controlled Standing Mode (SE + button 4)**, then to **Position Hold Mode (SE + button 2)**, and verify that the robot's joints are fully locked (Figure 7).
2. Attach the hoist hooks to the robot's lifting rings and secure the latches, then raise the hoist arm; verify that the robot's feet are clear of the ground with its limbs hanging naturally (Figure 8)
3. Press and hold the power button; once the power indicator goes out, the shutdown is successful.successfully powered off when the head display turns off

For return-to-box operations, please scan the QR code to view the complete product manual

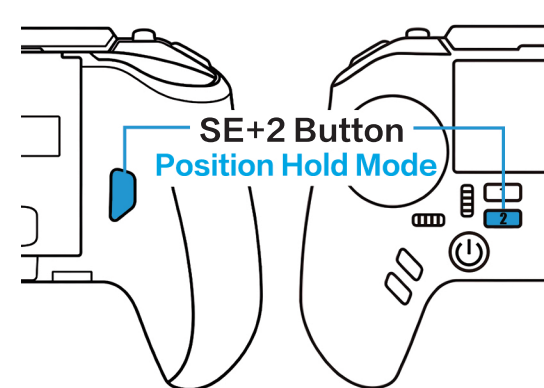


Figure 7

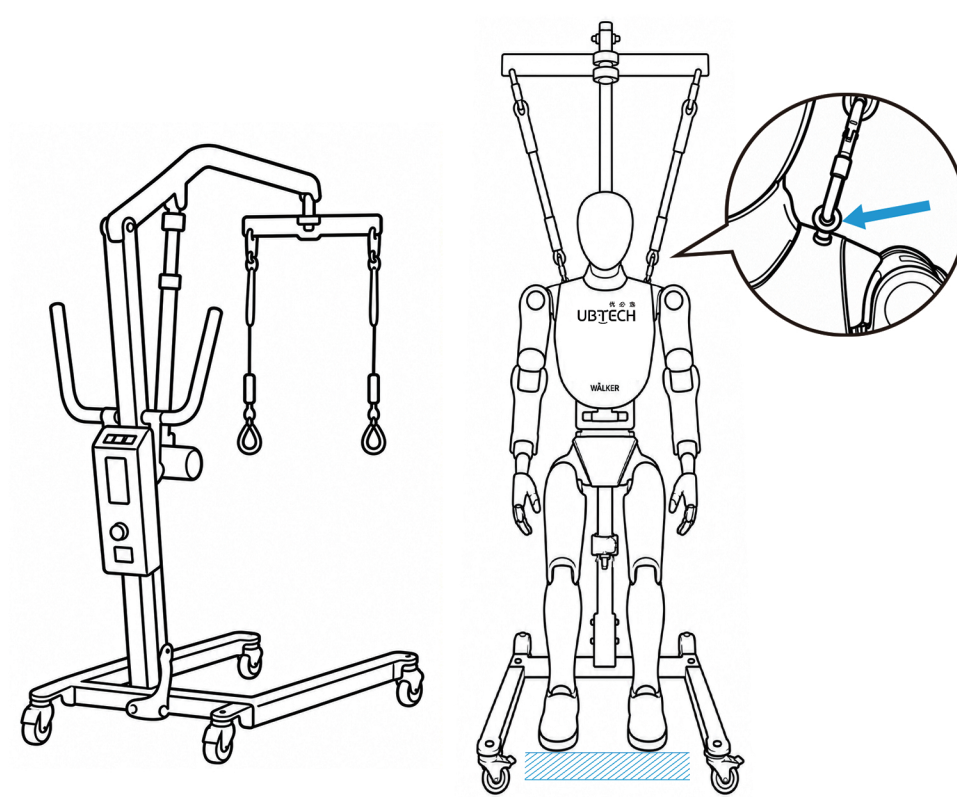


Figure 8

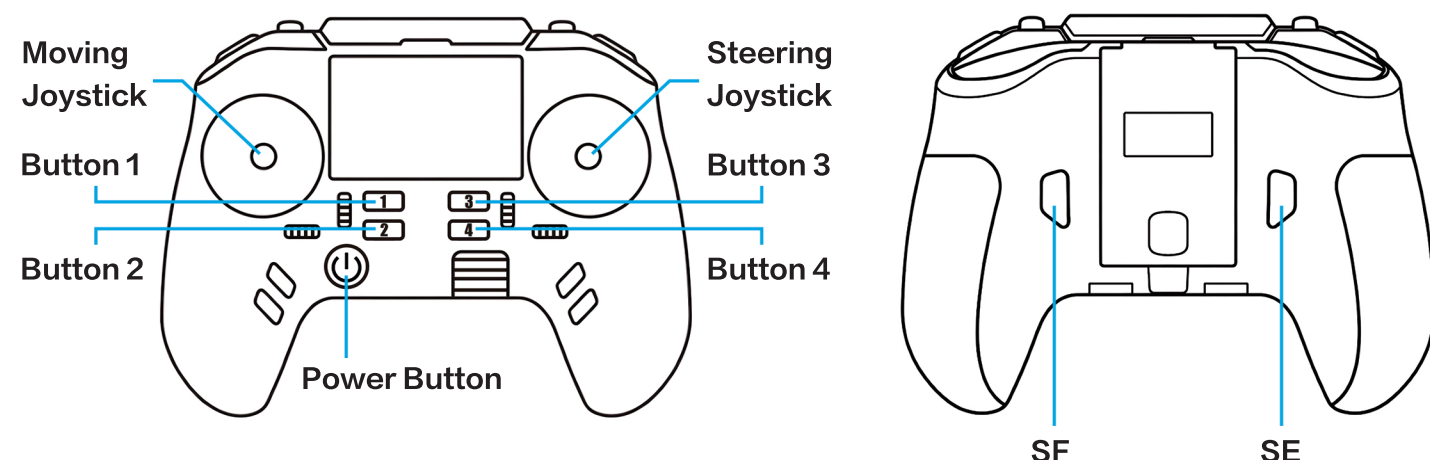


Figure 9

6 Remote Control Operations

- SE + Button 1: Home Position + Fold Legs
- SE + Button 2: Position Hold Mode
- SE + Button 4: Force-Controlled Standing Mode
- Button 1: Switch to Walking Gait
- SE + push left stick up/down: Move Forward/Backward
- SE + push left stick left/right: Move Left/Right
- SE + push right stick left/right: Turn Left/Right
- Hold SE and push T4 left: Unboxing Mode

For more remote control operations, please scan the QR code to view the complete product manual

Packing List

- Robot Body * 1
- Remote Controller * 1 pc
- Model Hands * 1 pair
- Power Adapter * 1 pc
- Battery * 1 pc (Built-in)
- Battery Direct Charging Adapter Cable * 1 pc
- Servo Emergency Stop Cable * 1 pc
- Back Handle * 1 pc
- Lifting Ring * 1 set
- Quick Start Guide * 1 pc
- Certificate of Conformity * 1 pc



User Manual